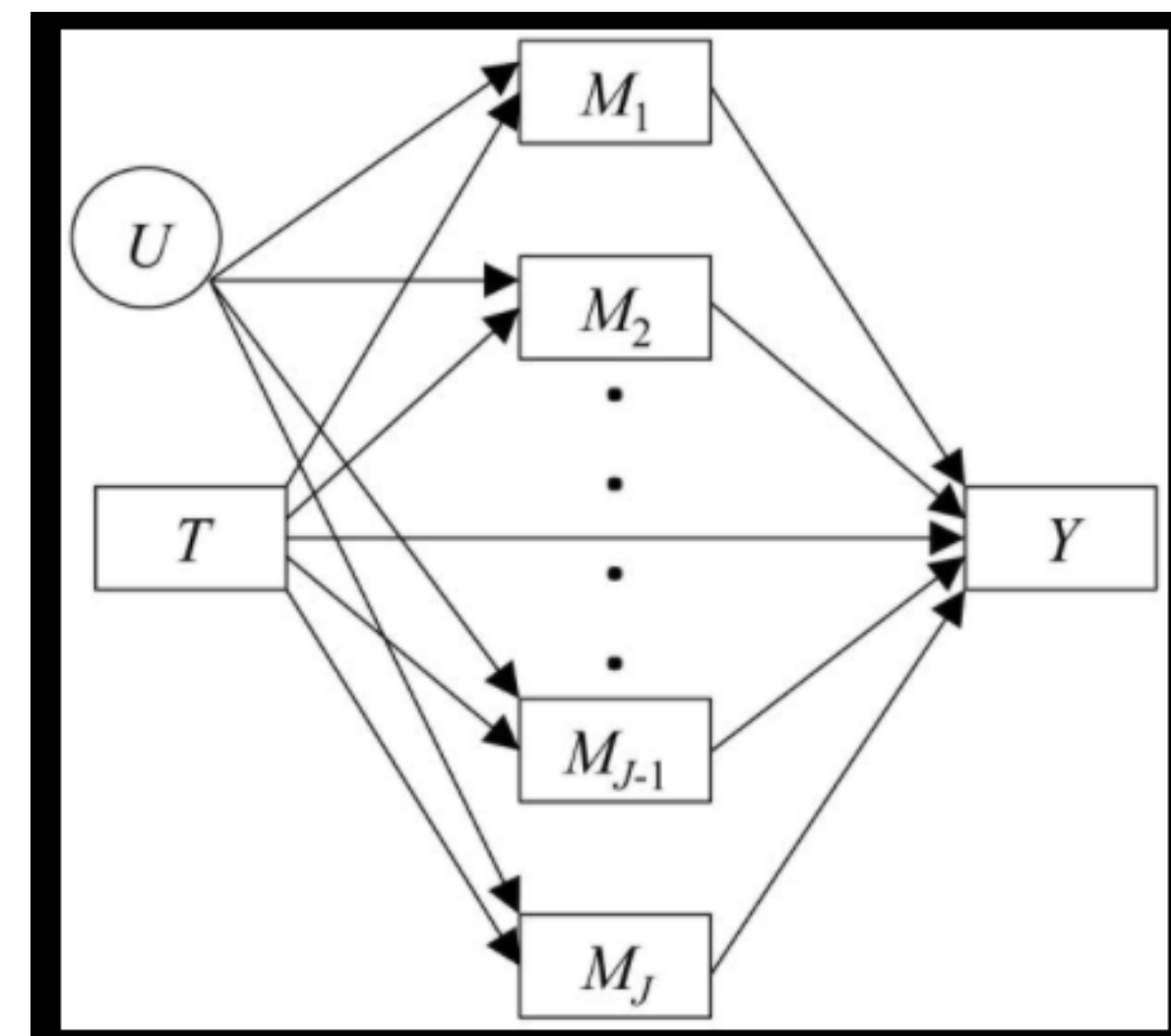
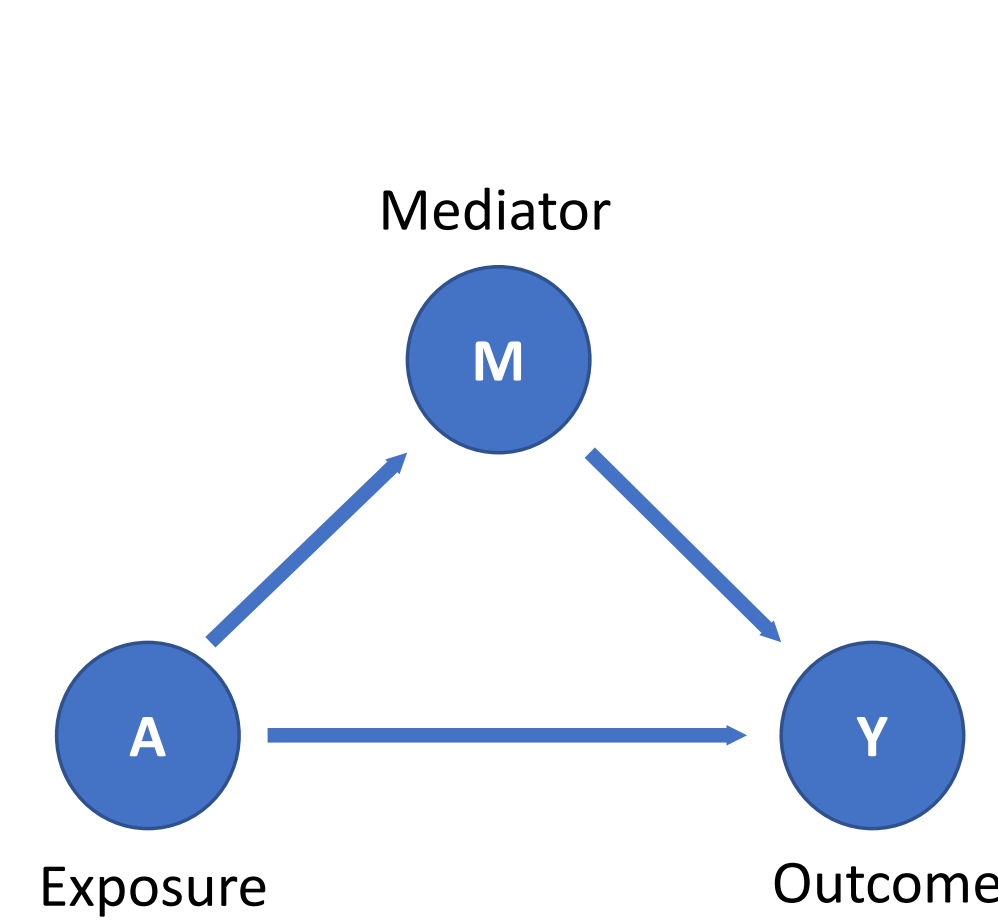


# A Bayesian nonparametric approach for causal inference with multiple mediators

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## Story so far...



2013, Wang et al.

$$\text{logit}(\Pr(Y=1)) = \beta_0 + \beta_1 M_1 + \dots + \beta_J M_J + \beta_{J+1} T + \beta' W$$

$$M_j^{(a)} = \alpha_{j0} + \alpha_{j1} T + \alpha_j' W + \varepsilon_j, j=1, \dots, J.$$

$$IE = IE_1 + IE_2 + \dots + IE_{J+1} + IE_J$$

2013, Imai and Yamamoto

$$M_i = \alpha_M + \beta_M T_i + \xi_M' X_i + \varepsilon_{M_i}$$

$$W_i = \alpha_W + \beta_W T_i + \xi_W' X_i + \varepsilon_{W_i}$$

$$Y_i = \alpha_Y + \beta_Y T_i + \gamma M_i + \theta' W_i + \xi_Y' X_i + \varepsilon_{Y_i}$$

2014, VanderWeele and Vansteelandt

$$E[Y | a, \mathbf{m}, c] = \theta_0 + \theta_1 a + \theta_2^{(1)} m(1) + \theta_2^{(2)} m(2) + \dots + \theta_2^{(K)} m^{(K)} + \theta_4 c$$

$$E[M^{(i)} | a, c] = \beta_0^{(i)} + \beta_1^{(i)} a + \beta_2^{(i)'} \text{ for } i = 1, \dots, K.$$

2019, Sohn et al.

$$M_i = (m_0 \oplus a^T \oplus h^{X_i}) \oplus U_{1i}$$

$$Y_i = c_0 + c T_i + (\log M_i)^T b + g X_i + U_{2i}, \text{ subject to } b^T \mathbf{1}_k = 0,$$

These approaches suffer from **parametric misspecification** and assume that the joint mediation effect is the **sum** of the individual mediator's effects

## What we want to do?

- A flexible approach that **does not** suffer from parametric misspecification
- Estimate **all possible interaction effects** of the mediators instead of just the additive joint mediation effect

## Causal Effects and Identification

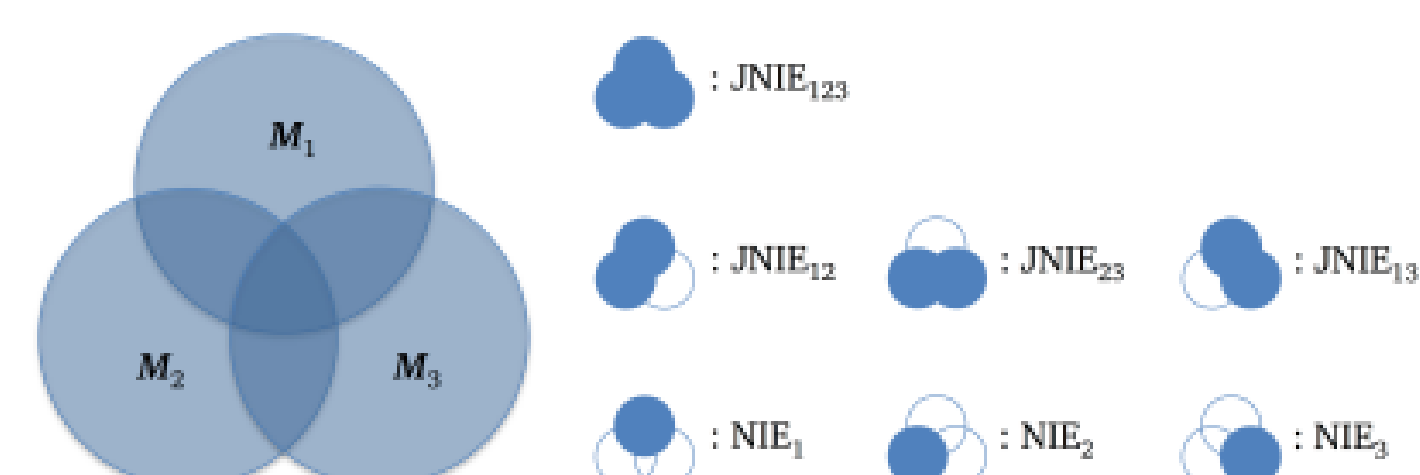
$$TE = E[Y(1, M(1, 1, \dots, 1)) - Y(0, M(0, 0, \dots, 0))]$$

$$NDE = E[Y(1, M(0, 0, \dots, 0)) - Y(0, M(0, 0, \dots, 0))]$$

$$JNIE = TE - NDE = E[Y(1, M(1, 1, \dots, 1)) - Y(1, M(0, 0, \dots, 0))]$$

$$JNIE_1 = E[Y(1, M(1, 1, 1)) - Y(1, M(0, 1, 1))]$$

$$JNIE_{12} = E[Y(1, M(1, 1, 1)) - Y(1, M(0, 0, 1))]$$



## Causal Effects and Identification (Cont.)

**Assumption 1**  $\{Y(a, M(a, a, \dots, a)), M(0, 0, \dots, 0), M(1, 1, \dots, 1)\} \perp\!\!\!\perp A | L = \ell$ .

**Assumption 2** For exposure  $A = 1$ , the conditional distributions of the observable potential outcome  $Y(1, M(1, 1, \dots, 1))$  given values of all potential mediators (and confounders), is the same as that of a priori counterfactual  $Y(1, M(0, 0, \dots, 0))$ , regardless of whether the mediator values were induced by  $A = 1$  or  $A = 0$ .

the above assumption implies that,

$$f_{1, M(0, 0, \dots, 0)}(y | M(0, 0, \dots, 0) = m, L = \ell) = f_{1, M(1, 1, \dots, 1)}(y | M(1, 1, \dots, 1) = m, L = \ell).$$

**Assumption 3**  $M_{j_1}(a) \perp\!\!\!\perp M_{j_2}(a') | L$  for  $a \neq a'$  and  $j_1, j_2 = 1, 2, \dots, Q$

**Theorem 1** Under the above assumptions, the NDE, JNIE ( and its various decompositions) are identifiable.

## BNP Model for the observed data

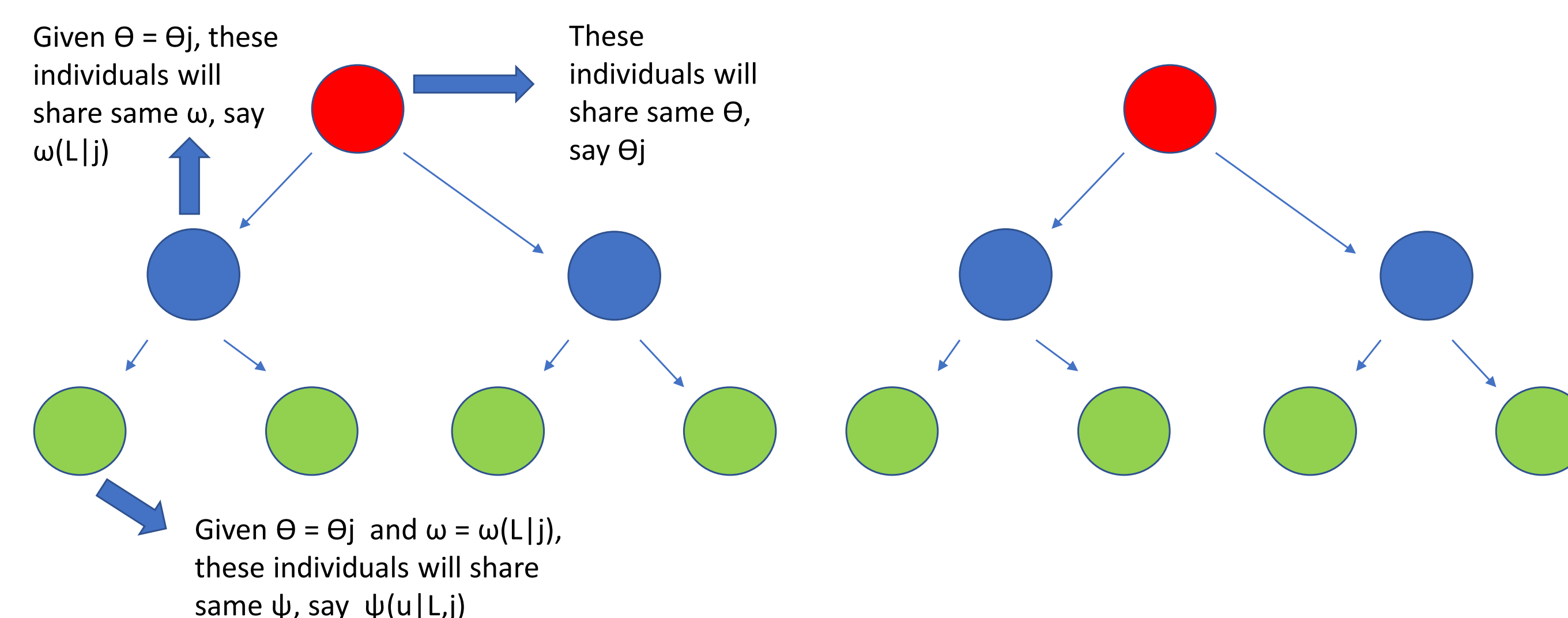
$$Y_i | M_i, X_i; \theta_i \sim p(y | m, x; \theta_i)$$

$$M_{iq} | X_i; \omega_i \sim p(m_q | x; \omega_i) : q = 1, \dots, Q$$

$$X_{i,r} | \psi_i \sim p(x_r | \psi_i) : r = 1, \dots, p+1,$$

$$(\theta_i, \omega_i, \psi_i) | P \sim P, \quad P \sim EDP3(\alpha_\theta, \alpha_\omega, \alpha_\psi, P_0).$$

$P \sim EDP3(\alpha_\theta, \alpha_\omega, \alpha_\psi, P_0)$  means that  $P_\theta \sim DP(\alpha_\theta, P_{0,\theta})$ ,  $P_\omega | \theta \sim DP(\alpha_\omega, P_{0,\omega | \theta})$ , and  $P_\psi | \theta, \omega \sim DP(\alpha_\psi, P_{0,\psi | \theta, \omega})$  with base measure  $P_0 = P_{0,\theta} \times P_{0,\omega | \theta} \times P_{0,\psi | \theta, \omega}$  (Enriched Dirichlet Process).



- Assume (local / within cluster) generalized linear models for  $Y_i | M_i, X_i; \theta_i$  and  $M_{iq} | X_i; \omega_i$  and  $K(y_i | m_i, x_i; \theta_j)$  and  $K(m_i | x_i; \omega_{lj})$
- Given  $\psi_i$  (that means a particular third level cluster), the  $(p+1)$  covariates,  $X_{i,1}, X_{i,2}, \dots, X_{i,(p+1)}$  are assumed to be "locally" (that is, intra-cluster) independent
- Similarly, given  $\omega_i$  (that means a particular second level cluster) and conditional on the covariates  $X_i$ , the  $Q$  mediators  $M_{i1}, M_{i2}, \dots, M_{iQ}$  are assumed to be "locally" independent

**Question:** What happens "globally" ?

## BNP Model (Cont.)

• Joint distribution:

$$f(y_i, m_i, x_i | P) = \sum_{j=1}^{\infty} \pi_j K(y_i | m_i, x_i; \theta_j) \sum_{l=1}^{\infty} \pi_{lj} K(m_i | x_i; \omega_{lj}) \sum_{u=1}^{\infty} \pi_{u|j,l} K(x_i | \psi_{u|j,l}).$$

where  $\pi_j = \pi_j' \prod_{j' < j} (1 - \pi_{j'})$ ,  $\pi_{lj} = \pi_{lj}' \prod_{l' < l} (1 - \pi_{l'j})$  and  $\pi_{u|j,l} = \pi_{u|j,l}' \prod_{u' < u} (1 - \pi_{u'|j,l})$  with  $\pi_j' \sim \text{Beta}(1, \alpha_\theta)$ ,  $\pi_{lj}' \sim \text{Beta}(1, \alpha_\omega)$  and  $\pi_{u|j,l}' \sim \text{Beta}(1, \alpha_\psi)$

• Conditional distribution of  $Y$  given  $M$  and  $X$ :

$$f(y | m, x) = \sum_{j=1}^{\infty} W_j(m, x) \cdot K(y | m, x; \theta_j)$$

where,

$$W_j(m, x) = \frac{\pi_j \sum_{l=1}^{\infty} \pi_{lj} K(m | x; \omega_{lj}) \sum_{u=1}^{\infty} \pi_{u|j,l} K(x | \psi_{u|j,l})}{\sum_{h=1}^{\infty} \pi_h \sum_{l=1}^{\infty} \pi_{lh} K(m | x; \omega_{lh}) \sum_{u=1}^{\infty} \pi_{u|h,l} K(x | \psi_{u|h,l})}$$

• Conditional distribution of  $M$  given  $X$ :

$$f(m | x) = \sum_{j=1}^{\infty} \sum_{l=1}^{\infty} W_{j,l}(x) \cdot K(m | x; \omega_{lj})$$

where,

$$W_{j,l}(x) = \frac{\pi_j \pi_{lj} \sum_{u=1}^{\infty} \pi_{u|j,l} K(x | \psi_{u|j,l})}{\sum_{h=1}^{\infty} \sum_{g=1}^{\infty} \pi_h \pi_{hg} \sum_{u=1}^{\infty} \pi_{u|h,g} K(x | \psi_{u|h,g})}$$

Thus, although the local regression models  $K(y | m, x; \theta_j)$  and  $K(m | x; \omega_{lj})$  are generalized linear models, the global regression models  $f(y | m, x)$  and  $f(m | x)$  are **computationally tractable, flexible, non-linear, non-additive models**.

## Computation

MCMC: Data, priors on cluster-specific parameters  $\rightarrow$  at each iteration, first update cluster membership (Algorithm 8 of [?]) and then update the cluster-specific parameters  $\rightarrow$  store them

**Post-processing computation:**

- Draw cluster and then draw the covariates
- Given the covariates from the previous step in (a), draw an  $m$ -subcluster and subsequently draw the mediators in such a way that the  $q^{\text{th}}$  mediator is induced under the treatment status  $a_q$ , for some fixed  $\{a_1, a_2, \dots, a_Q\} \in \{0, 1\}$
- Given the values from (a) and (b), compute  $E(Y | A = a, L = l, M = m, \theta^*, \omega^*, \psi^*, s)$
- Repeat (a)-(c)  $T$  times and use MC Integration to compute  $E(Y(a, M(a_1, a_2, \dots, a_Q)))$